# Modern Kernel Methods in Machine Learning: Part I

#### Danica J. Sutherland (she/her) Computer Science, University of British Columbia ETICS "summer" school, Oct 2022

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- Kernels are basically a way to study doing this with any, potentially very complicated,  $\phi$
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- $\phi$  will live in a *reproducing kernel Hilbert space*

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• Complete: "well-behaved" (Cauchy sequences have limits in  $\mathcal{H}$ )

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- Linear kernel on  $\mathbb{R}^d$  :  $k(x,y) = \langle x,y 
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• Is 
$$k_1(x,y) - k_2(x,y)$$
 necessarily a kernel?  
• Take  $k_1(x,y) = 0$ ,  $k_2(x,y) = xy$ ,  $x 
eq 0$ .

• Then 
$$k_1(x,x)-k_2(x,x)=-x^2<0$$

• But 
$$k(x,x) = \|\phi(x)\|_{\mathcal{H}}^2 \geq 0.$$

• A symmetric function  $k:\mathcal{X} imes\mathcal{X} o\mathbb{R}$  (i.e. have k(x,y)=k(y,x)) is positive semi-definite (psd) if for all  $n\geq 1$ ,  $(a_1,\ldots,a_n)\in\mathbb{R}^n$ ,  $(x_1,\ldots,x_n)\in\mathcal{X}^n$ ,

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• Equivalently: *kernel matrix*  $oldsymbol{K}$  is PSD

$$K := egin{bmatrix} k(x_1, x_1) & k(x_1, x_2) & \dots & k(x_1, x_n) \ k(x_2, x_1) & k(x_2, x_2) & \dots & k(x_2, x_n) \ dots & dots & \ddots & dots \ k(x_n, x_1) & k(x_n, x_2) & \dots & k(x_n, x_n) \end{bmatrix}$$

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- Hilbert space kernels are psd
- psd functions are Hilbert space kernels
  - Moore-Aronszajn Theorem; we'll come back to this

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  - Let  $V \sim \mathcal{N}(0,K_1)$ ,  $W \sim \mathcal{N}(0,K_2)$  be independent
  - $\operatorname{Cov}(V_iW_i,V_jW_j)=\operatorname{Cov}(V_i,V_j)\operatorname{Cov}(W_i,W_j)=k_{ imes}(x_i,x_j)$
  - Covariance matrices are psd, so  $k_{ imes}$  is too

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- Exponents:  $k_{ ext{exp}}(x,y) = \exp(k(x,y))$  is pd
- If  $f:\mathcal{X}
  ightarrow\mathbb{R}$ ,  $k_f(x,y)=f(x)k(x,y)f(y)$  is pd
  - Use the feature map  $x\mapsto f(x)\phi(x)$

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$$= \exp \Big( - rac{1}{2\sigma^2} ig[ \|x\|^2 - 2x^{\mathsf{T}}y + \|y\|^2 ig] \Big)$$

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, the Gaussian kernel
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• Recall original motivating example with

$$\mathcal{X}=\mathbb{R} \qquad \phi(x)=(1,x,x^2)\in \mathbb{R}^3$$

• Kernel is  $k(x,y) = \langle \phi(x), \phi(y) 
angle_{\mathcal{H}} = 1 + xy + x^2y^2$ 



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- Reproducing prop.:  $f(x) = \langle f(\cdot), \phi(x) 
  angle_{\mathcal{H}}$  for  $f \in \mathcal{H}$

# **Reproducing kernel Hilbert space (RKHS)**

• Every psd kernel k on  $\mathcal{X}$  defines a (unique) Hilbert space, its RKHS  $\mathcal{H}$ , and a map  $\phi:\mathcal{X}\to\mathcal{H}$  where

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- Combining the two, we sometimes write  $k(x,\cdot)=\phi(x)$
- $k(x, \cdot)$  is the evaluation functional An RKHS is defined by it being *continuous*, or

$$|f(x)| \leq M_x \|f\|_{\mathcal{H}}$$

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  - Can also show uniqueness
- Theorem: k is psd iff it's the reproducing kernel of an RKHS

## A quick check: linear kernels

• 
$$k(x,y) = x^{\mathsf{T}}y$$
 on  $\mathcal{X} = \mathbb{R}^d$   
•  $k(x,\cdot) = [y \mapsto x^{\mathsf{T}}y]$  "corresponds to"  $x$   
• If  $f(y) = \sum_{i=1}^n a_i k(x_i,y)$ , then  $f(y) = [\sum_{i=1}^n a_i x_i]^{\mathsf{T}}y$ 

- Closure doesn't add anything here, since  $\mathbb{R}^d$  is closed
- So, linear kernel gives you RKHS of linear functions

$$ullet \ \|f\|_{\mathcal{H}} = \sqrt{\sum_{i=1}^n \sum_{j=1}^n a_i a_j k(x_i, x_j)} = \|\sum_{i=1}^n a_i x_i\|_{\mathcal{H}}$$

$$k(x,y) = \exp(rac{1}{2\sigma^2} \|x-y\|^2)$$



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- ${\cal H}$  is infinite-dimensional
- Functions in  $\mathcal H$  are bounded:  $f(x) = \langle f, k(x, \cdot) 
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- Choice of  $\sigma$  controls how fast functions can vary:

$$f(x+t)-f(x)\leq \|k(x+t,\cdot)-k(x',\cdot)\|_{\mathcal{H}}\|f\|_{\mathcal{H}} \ \|k(x+t,\cdot)-k(x,\cdot)\|_{\mathcal{H}}^2 = 2-2k(x,x+t) = 2-2\expigg(-rac{\|t\|^2}{2\sigma^2}igg)$$



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• Can say lots more with Fourier properties

$$\hat{f} = rgmin_{f \in \mathcal{H}} rac{1}{n} \sum_{i=1}^n (f(x_i) - y_i)^2 + \lambda \|f\|_{\mathcal{H}}^2$$

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Linear kernel gives normal ridge regression:

$$\hat{f}\left(x
ight) = \hat{w}^{\mathsf{T}}x; \hspace{1em} \hat{w} = rgmin_{w\in \mathbb{R}^d} rac{1}{n} \sum_{i=1}^n (w^{\mathsf{T}}x_i - y_i)^2 + \lambda \|w\|^2$$

Nonlinear kernels will give nonlinear regression!

$$\hat{f} = rgmin_{f\in\mathcal{H}} rac{1}{n} \sum_{i=1}^n (f(x_i) - y_i)^2 + \lambda \|f\|_\mathcal{H}^2$$

How to find  $\hat{f}$  ?

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How to find  $\hat{f}$  ? Representer Theorem

• Let  $\mathcal{H}_X = ext{span}\{k(x_i,\cdot)\}_{i=1}^n$  $\mathcal{H}_\perp$  its orthogonal complement in  $\mathcal{H}$ 

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- Let  $\mathcal{H}_X = ext{span}\{k(x_i,\cdot)\}_{i=1}^n$  $\mathcal{H}_\perp$  its orthogonal complement in  $\mathcal{H}$
- Decompose  $f=f_X+f_\perp$  with  $f_\mathcal{X}\in\mathcal{H}_X$  ,  $f_\perp\in\mathcal{H}_\perp$

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- $ullet \ \|f\|^2_{{\mathcal H}} = \|f_X\|^2_{{\mathcal H}} + \|f_ot\|^2_{{\mathcal H}}$
- Minimizer needs  $f_{\perp}=0$ , and so  $\hat{f}=\sum_{i=1}^n lpha_i k(x_i,\cdot)$

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How to find  $\hat{f}$  ? Representer Theorem:  $\hat{f} = \sum_{i=1}^n \hat{lpha}_i k(x_i, \cdot)$ 

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ight)^2 = \sum_{i=1}^n \left([Klpha]_i-y_i
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$$\hat{lpha} = rgmin_{lpha \in \mathbb{R}^n} lpha^\mathsf{T} K^2 lpha - 2 y^\mathsf{T} K lpha + y^\mathsf{T} y + n \lambda lpha^\mathsf{T} K lpha$$

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How to find  $\hat{f}$  ? Representer Theorem:  $\hat{f} = \sum_{i=1}^n \hat{lpha}_i k(x_i, \cdot)$ 

$$egin{aligned} \hat{lpha} &= rg\min lpha^{\mathsf{T}} K^2 lpha - 2 y^{\mathsf{T}} K lpha + y^{\mathsf{T}} y + n \lambda lpha^{\mathsf{T}} K lpha \ &= rg\min lpha^{\mathsf{T}} K (K + n \lambda I) lpha - 2 y^{\mathsf{T}} K lpha \ &lpha \in \mathbb{R}^n \end{aligned}$$

Setting derivative to zero gives  $K(K+n\lambda I)\hat{lpha}=Ky,$  satisfied by  $\hat{lpha}=(K+n\lambda I)^{-1}y$ 

## **Other kernel algorithms**

• Representer theorem applies if R is strictly increasing in

$$\min_{f\in\mathcal{H}}L(f(x_1),\cdots,f(x_n))+R(\|f\|_{\mathcal{H}})$$

- Kernel methods can then train based on kernel matrix  $oldsymbol{K}$
- Classification algorithms:
  - Support vector machines: L is hinge loss
  - Kernel logistic regression: L is logistic loss
- Principal component analysis, canonical correlation analysis
- Many, many more...
- But not everything works...e.g. Lasso  $\|w\|_1$  regularizer

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- Difficulty of learning is controlled by RKHS norm of target

• One definition: a continuous kernel on a compact metric space  $\mathcal{X}$  is **universal** if  $\mathcal{H}$  is  $L_{\infty}$ -dense in  $C(\mathcal{X})$ : for every continuous  $g: \mathcal{X} \to \mathbb{R}$ , for every  $\varepsilon > 0$ , there is an  $f \in \mathcal{H}$  with  $\|f - g\|_{\infty} = \sup_{x \in \mathcal{X}} |f(x) - g(x)| \leq \varepsilon$ 

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- Never true for finite-dim kernels: need  $\mathrm{rank}(K) = n$

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- $\mathcal{O}(n^3)$  computational complexity,  $\mathcal{O}(n^2)$  memory
  - Various approximations you can make

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    - SVMs with NTK can be great on small data
  - Inspiration: learn the kernel model end-to-end
    - Ongoing area; good results in two-sample testing, GANs, density estimation, meta-learning, semisupervised learning, ...
    - Explored a bit in interactive session!

## What's next

- After break: interactive session exploring w/ ridge regression
- Tomorrow: a subset of
  - Representing distributions
    - Uses for statistical testing + generative models
  - Connections to Gaussian processes, probabilistic numerics
  - Approximation methods for faster computation
  - Deeper connection to deep learning
- More details on basics:
  - Berlinet and Thomas-Agnan, *RKHS in Probability and Statistics*
  - Steinwart and Christmann, *Support Vector Machines*